

# Servo solenoid valves with on-board electronics (OBE)

**RE 29077/01.05**  
Replaces: 01.03

1/16

## Type 4WRVE 10...25

Size 10, 16, 25

Unit series 2X

Maximum working pressure P, A, B 350 bar, T, X, Y 250 bar

Nominal flow rate 40...430 l/min ( $\Delta p$  10 bar)



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## Features

- Pilot operated High Response servo solenoid valves NG10 to NG25, with control piston and sleeve in servo quality
- On-board electronics (OBE) with position controller for the pilot and main stages, calibrated at the factory
- Main stage in servo quality with position feedback
- Flow characteristic
  - M = Progressive with fine metering notch
  - P = Non-linear curve
  - L = Linear (only available on request)
- Electrical connection 11P+PE  
Signal input difference amplifier with interface B5  $\pm 10$  V
- Suitable for electrohydraulic controllers in production and testing systems
- For subplate attachment, mounting hole configuration NG10 to ISO 4401-05-05-0-94, NG16 to ISO 4401-07-06-0-94 and NG25 to ISO 4401-08-07-0-94
- Subplates as per catalogue section, NG10 RE 45055, NG16 RE 45057 and NG25 RE 45059 (order separately)
- Line sockets to DIN 43563-AM6, see catalogue section RE 08008 (order separately)

## Variants on request

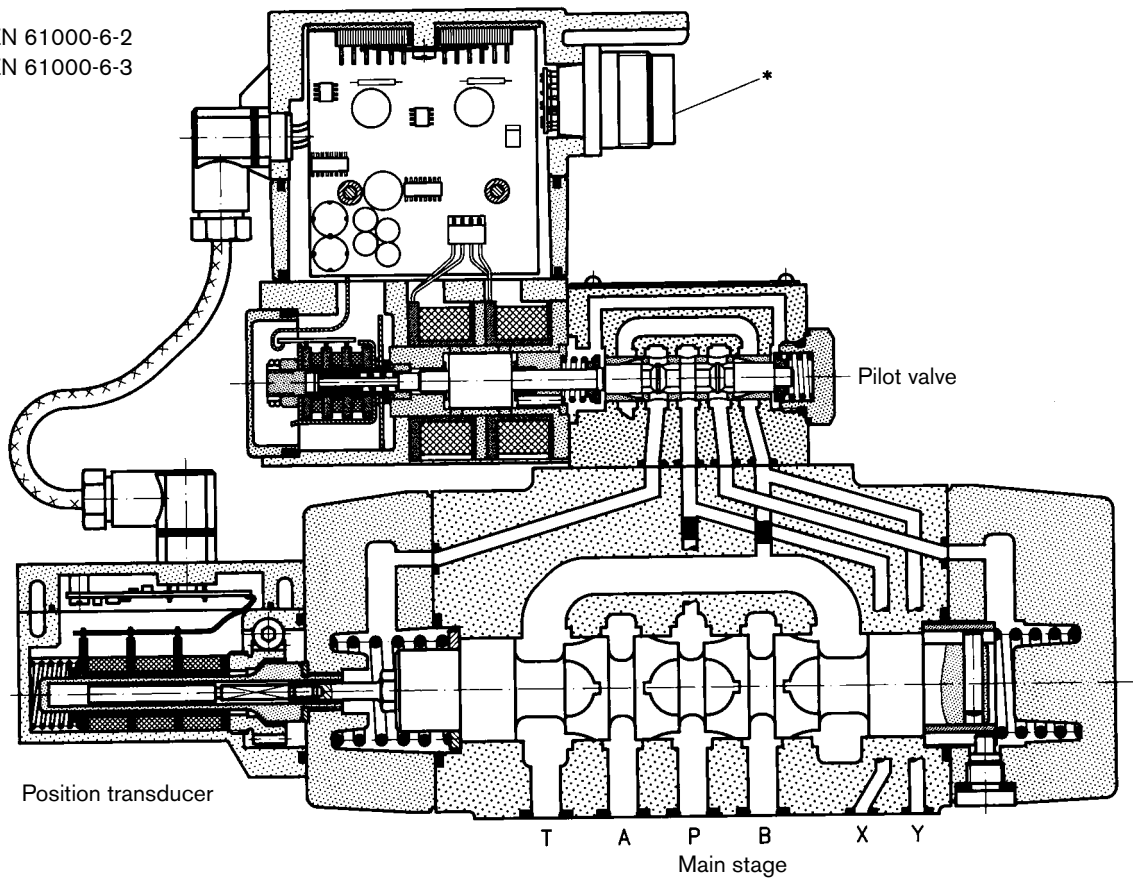
- For standard applications
- Special symbols for plastic injection-moulding machines and for extending the module.



**Function, sectional diagram**

**Servo solenoid valve 4WRVE 10...25**

CE EN 61000-6-2  
EN 61000-6-3



**Symbols**

	<p>M: Progressive with fine metering</p>	<p>P: Non-linear, linear (40%)</p>

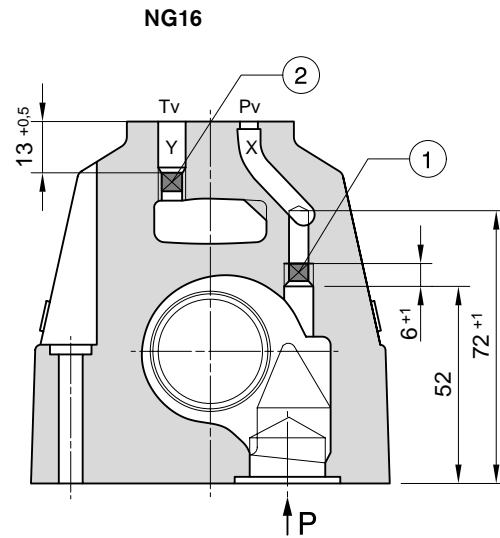
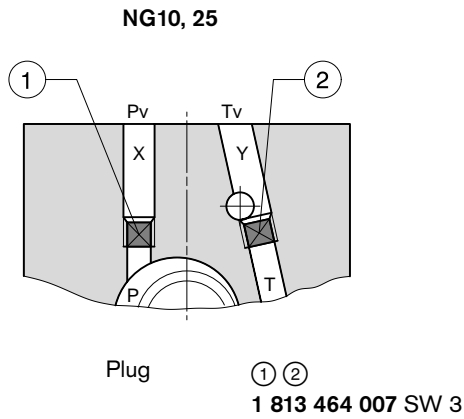
**Accessories, not included in scope of delivery**

<p>Fastening screws</p>	<table border="1"> <tr> <td>NG10</td> <td>4 x M6 x 40, DIN 912-10.9</td> <td><b>2 910 151 209</b></td> </tr> <tr> <td rowspan="2">NG16</td> <td>2 x M6 x 45, DIN 912-10.9</td> <td><b>2 910 151 211</b></td> </tr> <tr> <td>4 x M10 x 50, DIN 912-10.9</td> <td><b>2 910 151 301</b></td> </tr> <tr> <td>NG25</td> <td>6 x M12 x 60, DIN 912-10.9</td> <td><b>2 910 151 354</b></td> </tr> </table>	NG10	4 x M6 x 40, DIN 912-10.9	<b>2 910 151 209</b>	NG16	2 x M6 x 45, DIN 912-10.9	<b>2 910 151 211</b>	4 x M10 x 50, DIN 912-10.9	<b>2 910 151 301</b>	NG25	6 x M12 x 60, DIN 912-10.9	<b>2 910 151 354</b>	
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NG16	2 x M6 x 45, DIN 912-10.9	<b>2 910 151 211</b>											
	4 x M10 x 50, DIN 912-10.9	<b>2 910 151 301</b>											
NG25	6 x M12 x 60, DIN 912-10.9	<b>2 910 151 354</b>											
<p>*</p> <p>Pg16</p>	<p>Line socket 11P+PE, see also RE 08008</p>	<p>KS <b>1 834 484 142</b></p>											

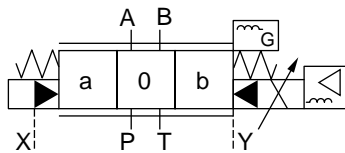
**Testing and service equipment**

- Test box type VT-PE-TB3, see RE 30065
- Test adapter 11P+PE type VT-PA-1, see RE 30067

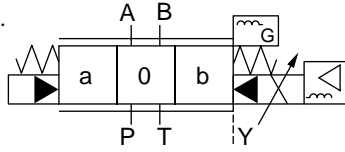
Control oil supply



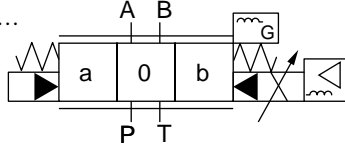
Type ... -3X ...



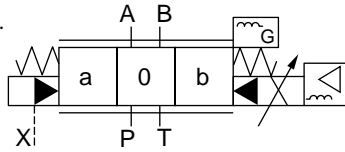
Type ... -3X ... E ...



Type ... -3X ... ET ...

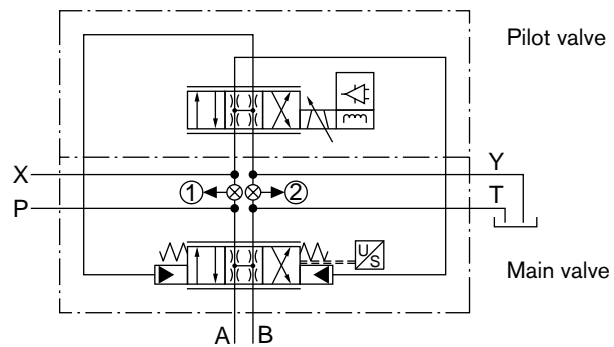


Type ... -3X ... T ...



- No designation = "x" = external, "y" = external
- E = "x" = internal, "y" = external
- ET = "x" = internal, "y" = internal
- T = "x" = external, "y" = internal

Symbol in detail



Conversion

The pilot valve can be supplied with oil both via ports X and Y (external) and from the main flow ducts P and T.  
 In the basic version, the valve is equipped with the plugs ① and ②, i.e. X and Y are external.  
 For valve versions with X and/or Y as internal, see ordering overview or carry out the conversion (see diagram above).  
 When the control oil supply or discharge is changed, the part number must also be changed.

Important




Servo solenoid valves (pilot operated) do not have a closed middle position when switched off! They only perform their function in an active, closed control loop, even when the pilot valve features a relief (fail-safe) 4th symbol.  
 For details on "switch-off behaviour", see Technical data.

## Technical data


### General

Construction	Spool type valve, pilot operated		
Actuation	4WREH servo solenoid valve NG6 – OBE, with position controller for pilot valve and main stage		
Type of mounting	Subplate, mounting hole configuration NG10...25 (ISO 4401-...)		
Installation position	Optional		
Ambient temperature range	°C	-20 ... +50	
Weight	kg	<b>NG10</b> 8.0	<b>NG16</b> 10.4 <b>NG25</b> 18.2
Vibration resistance, test condition	max. 25 g, shaken in 3 dimensions (24 h)		

### Hydraulic (measured with HLP 46, $\vartheta_{oil} = 40^\circ\text{C} \pm 5^\circ\text{C}$ )

Pressure fluid	Hydraulic oil to DIN 51524 ... 535, other fluids after prior consultation									
Viscosity range	recommended	mm <sup>2</sup> /s	20 ... 100							
	max. permitted	mm <sup>2</sup> /s	10 ... 800							
Pressure fluid temperature range	°C	-20 ... +65								
Maximum permissible degree of contamination of pressure fluid Purity class to ISO 4406 (c)	Class 18/16/13 <sup>1)</sup>									
Flow direction	See symbol									
Nominal flow at $\Delta p = 5$ bar per notch <sup>2)</sup>	l/min	<b>NG10</b>				<b>NG16</b>				<b>NG25</b>
		40	55	70	85	90	120	150	200	370
Max. working pressure	bar	Port P, A, B: 350								
Max. pressure	bar	Port T, X, Y: 250								
$q_{max.}$	l/min	170				450				900
$q_N$ pilot valve	l/min	8				24				40
Leakage of pilot valve at 100 bar	 cm <sup>3</sup> /min	<180				<300				<500
Leakage main valve at 100 bar	  cm <sup>3</sup> /min	<400	<600	<1,000				<1,000		
Control oil pressure "pilot stage"	bar	min. 10								
		max. 250								

### Static/Dynamic

Hysteresis	%	≤ 0.1, scarcely measurable		
Manufacturing tolerance for $q_{max.}$	%	< 10		
Response time for signal change (at X = 100 bar)	0 ... 100%	12	15	23
	0 ... 10%	6	7	10
Response time for signal change (at X = 10 bar)	0 ... 100%	40	50	90
	0 ... 10%	20	20	30
Switch-off behaviour	After electrical switch-off: pilot valve undefined in P-B/A-T or P-A/B-T Main stage can be controlled 100 % (PB/AT or PA/BT)			
Thermal drift	Zero point displacement < 1% at $\Delta T = 40^\circ\text{C}$			
Zero adjustment	Factory-set ± 1 %			
Conformity	 EN 61000-6-2 EN 61000-6-3			

<sup>1)</sup> The purity classes stated for the components must be complied with in hydraulic systems. Effective filtration prevents problems and also extends the service life of components. For a selection of filters, see catalogue sections RE 50070, RE 50076 and RE 50081.

<sup>2)</sup> Flow rate at a different  $\Delta p$   $q_x = q_{nom} \cdot \sqrt{\frac{\Delta p_x}{5}}$

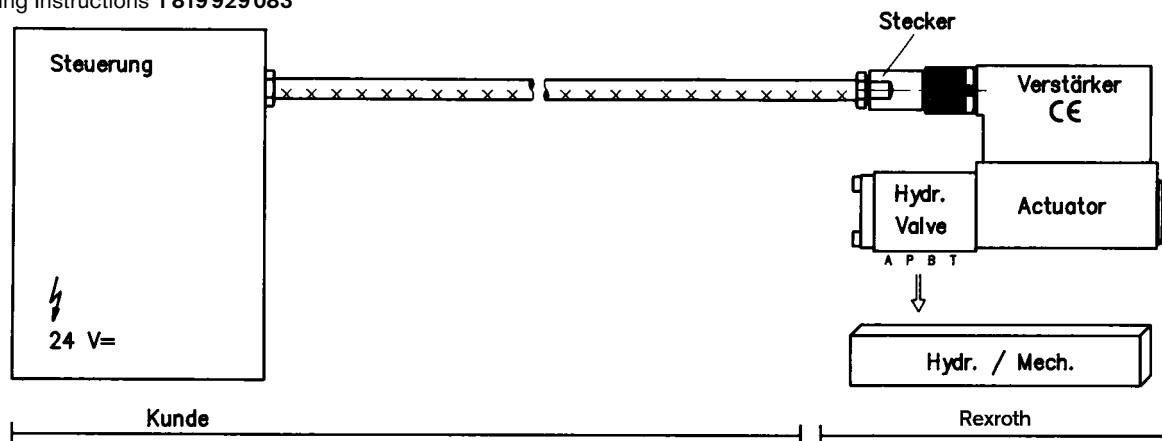
### Important

Pilot operated 4WRLE servo solenoid valves only perform their function in an active closed control loop and do not have a safe basic position when switched off. For this reason, many applications require the use of "additional check valves", which must be taken into account during the On/Off switching sequence.



## Connection

For electrical data, see page 6 and  
Operating Instructions 1 819 929 083



### Technical notes on the cable

- Version:**
- Multi-wire cable
  - Extra-finely stranded wire to VDE 0295, Class 6
  - Protective conductor, green/yellow
  - Cu braided screen
- Types:**
- e.g. Ölflex-FD 855 CP (from Lappkabel company)
- No. of wires:**
- Determined by type of valve, plug types and signal assignment
- Cable Ø:**
- 0.75 mm<sup>2</sup> to 20 m length
  - 1.0 mm<sup>2</sup> to 40 m length
- Outside Ø:**
- 9.4 ... 11.8 mm – Pg11
  - 12.7 ... 13.5 mm – Pg16

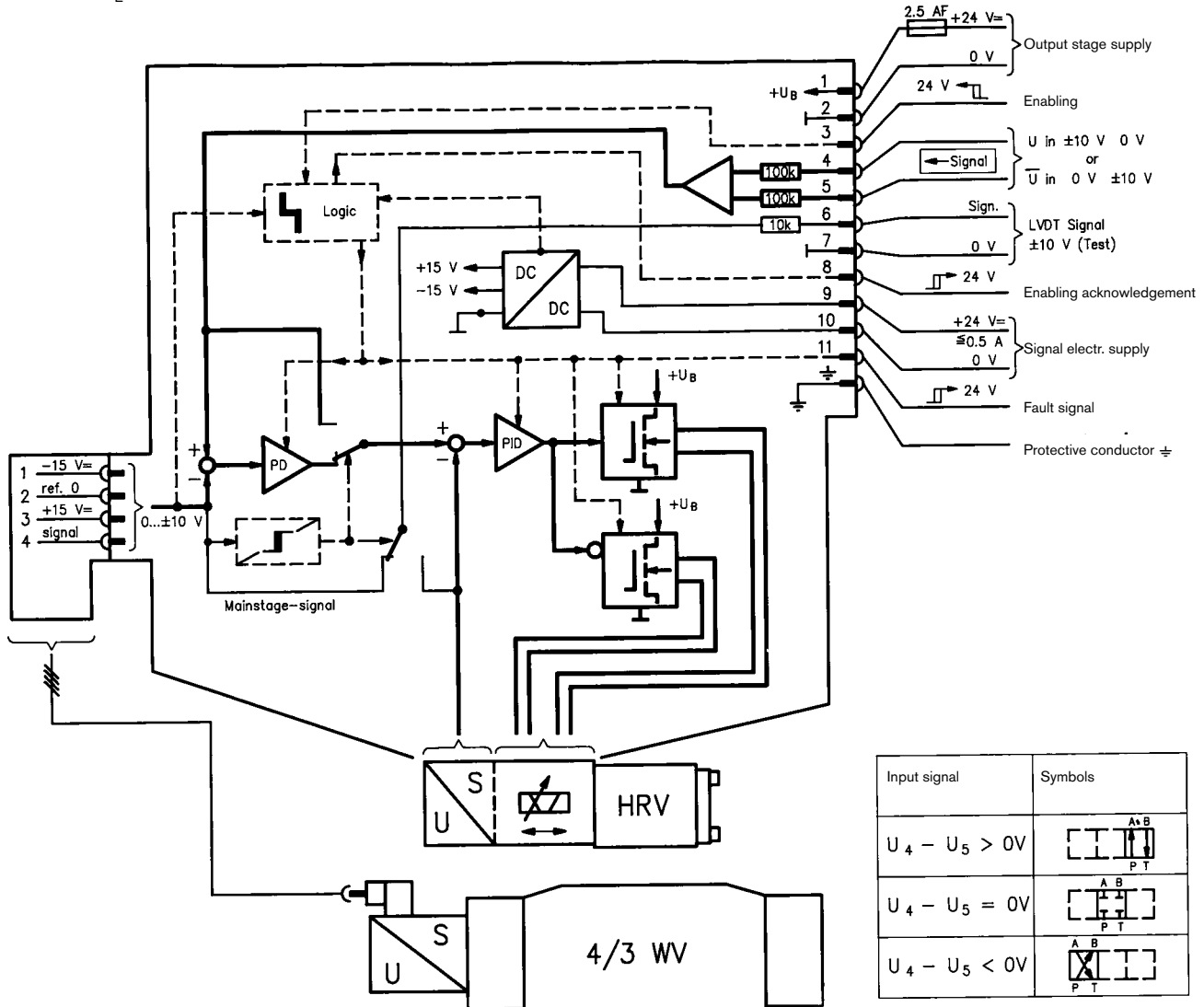
### Important

Electrical signals emitted via the trigger electronics (e.g. actual values) must not be used to shut down safety-relevant machine functions! (See European Standard, "Technical Safety Requirements for Fluid-Powered Systems and Components – Hydraulics", EN 982.)

### On-board trigger electronics

#### Block diagram/pin assignment

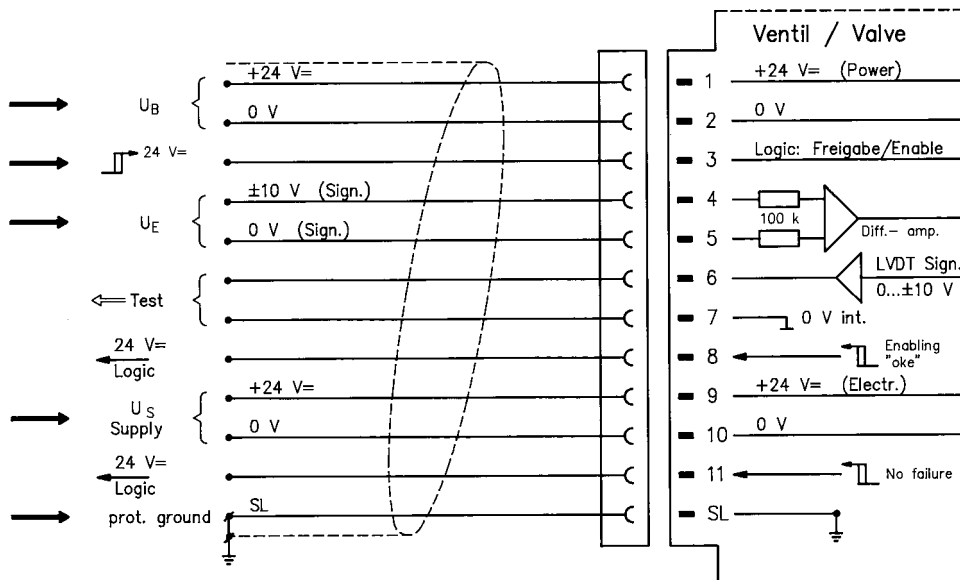
Version B5:  $U_E \pm 10V$



#### Pin assignment 11P+PE

Version B5:  $U_E \pm 10V$

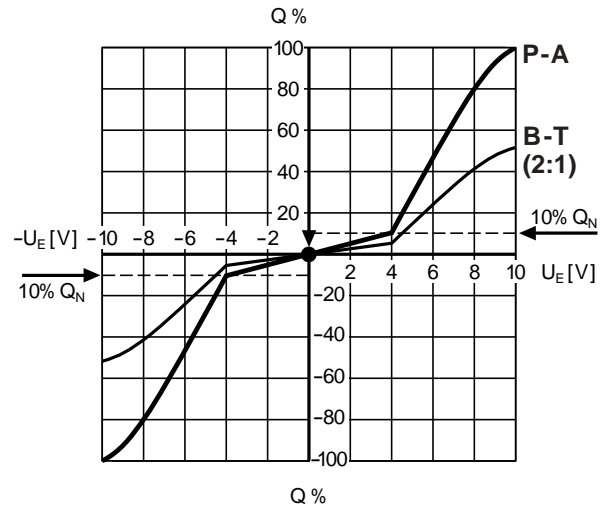
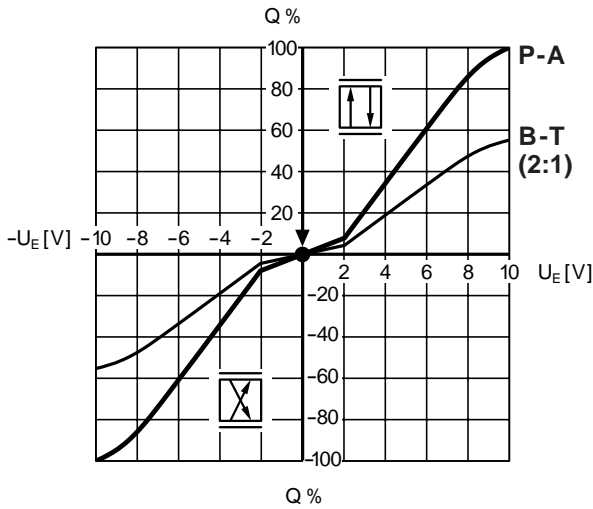
( $R_i = 100k\Omega$ )



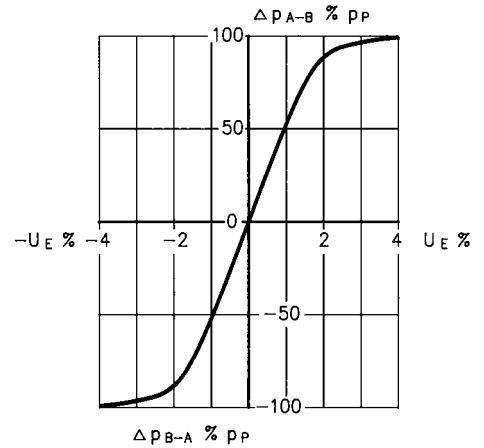
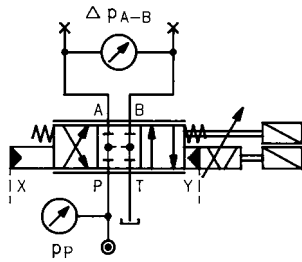
**Performance curves** (measured with HLP46,  $\vartheta_{oil} = 40^\circ\text{C} \pm 5^\circ\text{C}$ )

Flow rate/Signal function

$Q = f(U_E)$

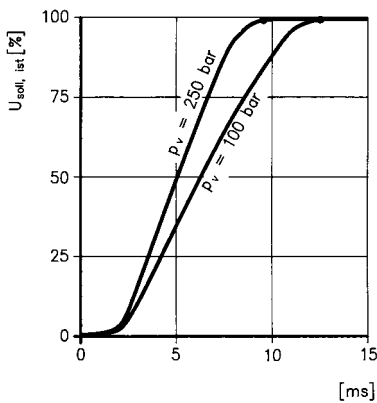


Pressure gain  $\Delta = f(U_E)$

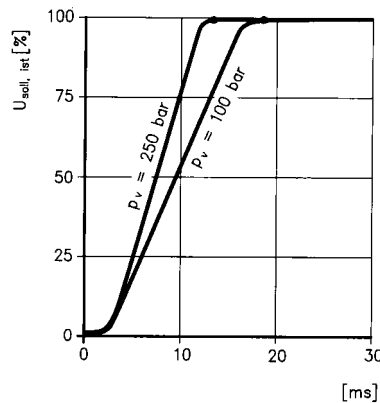


Response time 0 → 100%

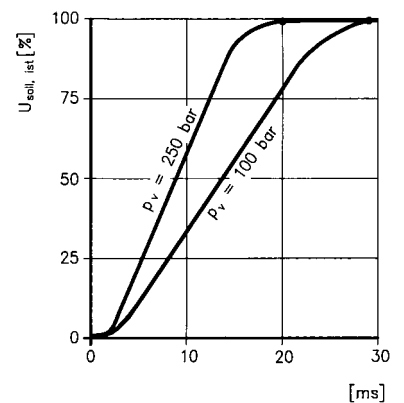
NG10



NG16

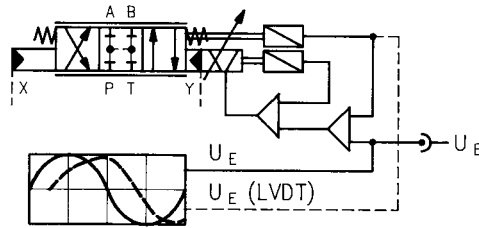


NG25



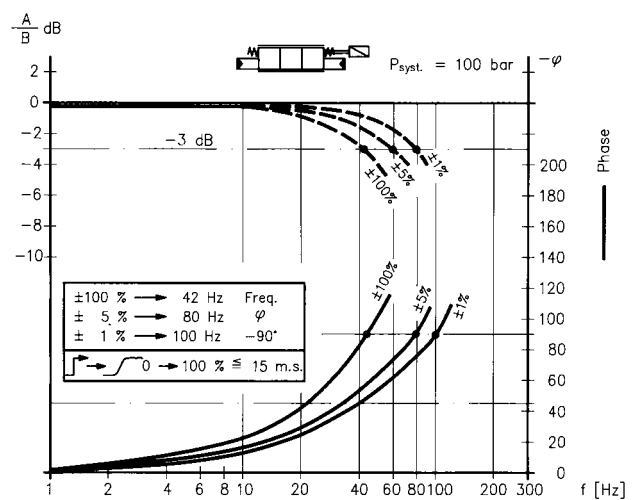
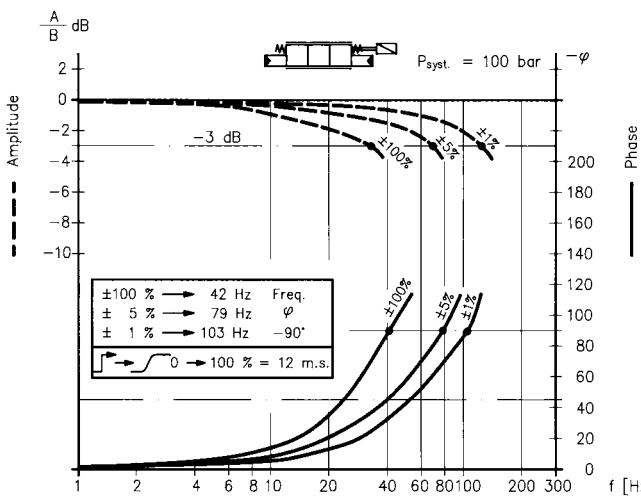
**Performance curves** (measured with HLP 46,  $\vartheta_{oil} = 40^\circ\text{C} \pm 5^\circ\text{C}$ )

**Bode diagrams**

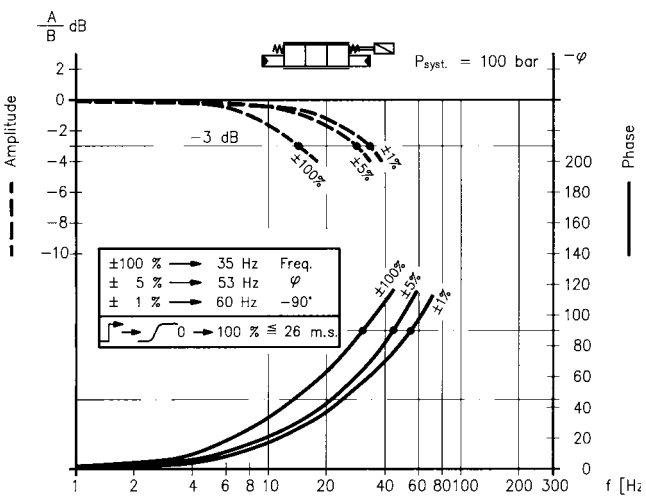


**NG10**

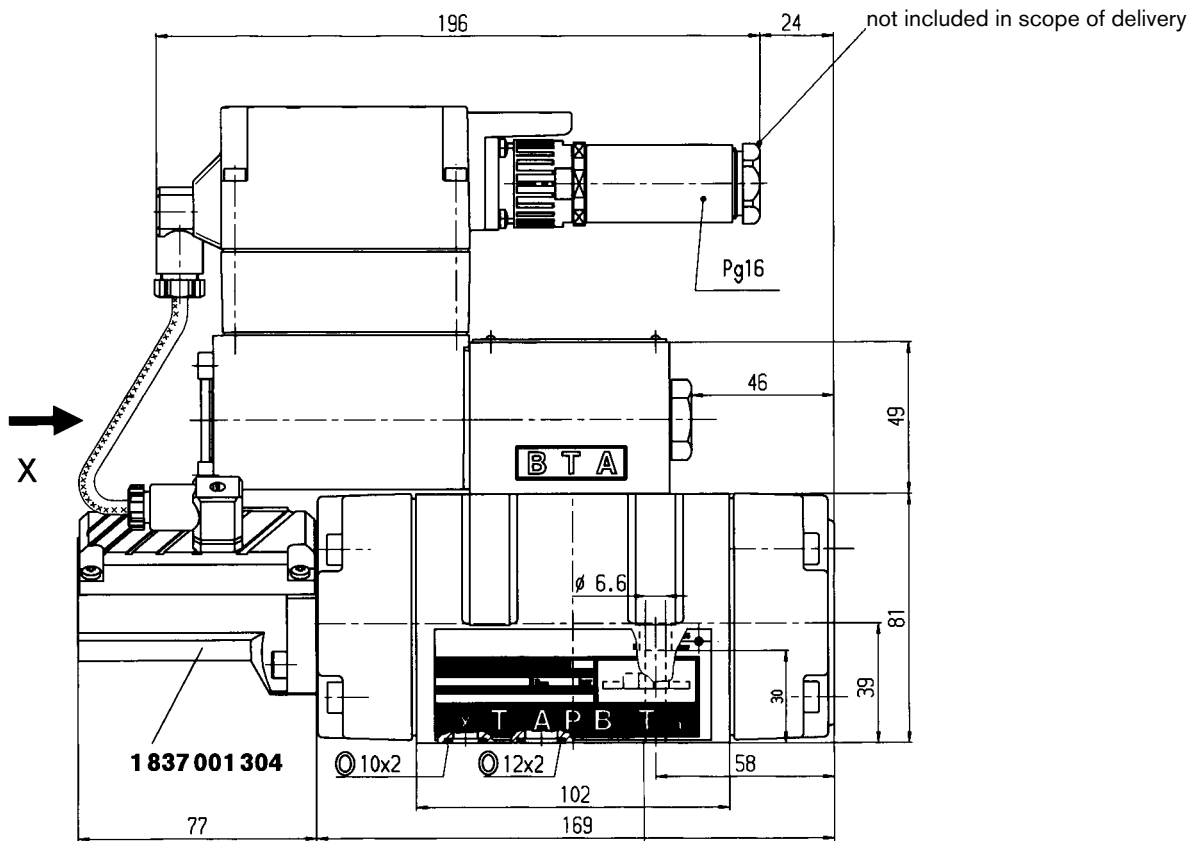
**NG16**




**NG25**

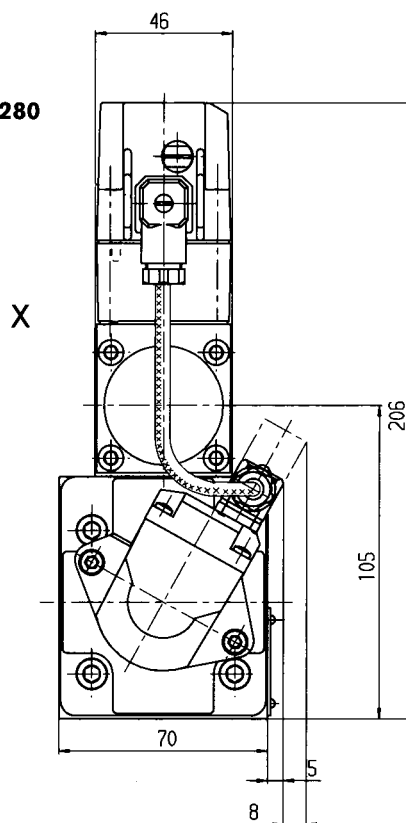


**Unit dimensions NG10 (nominal dimensions in mm)**



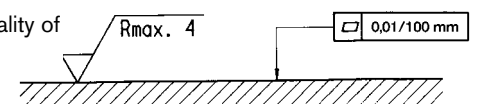
4 x  M6x40 DIN 912-10.9  
 = 11<sup>+3</sup> Nm **2910 151 209**

 Set **1817 010 280**

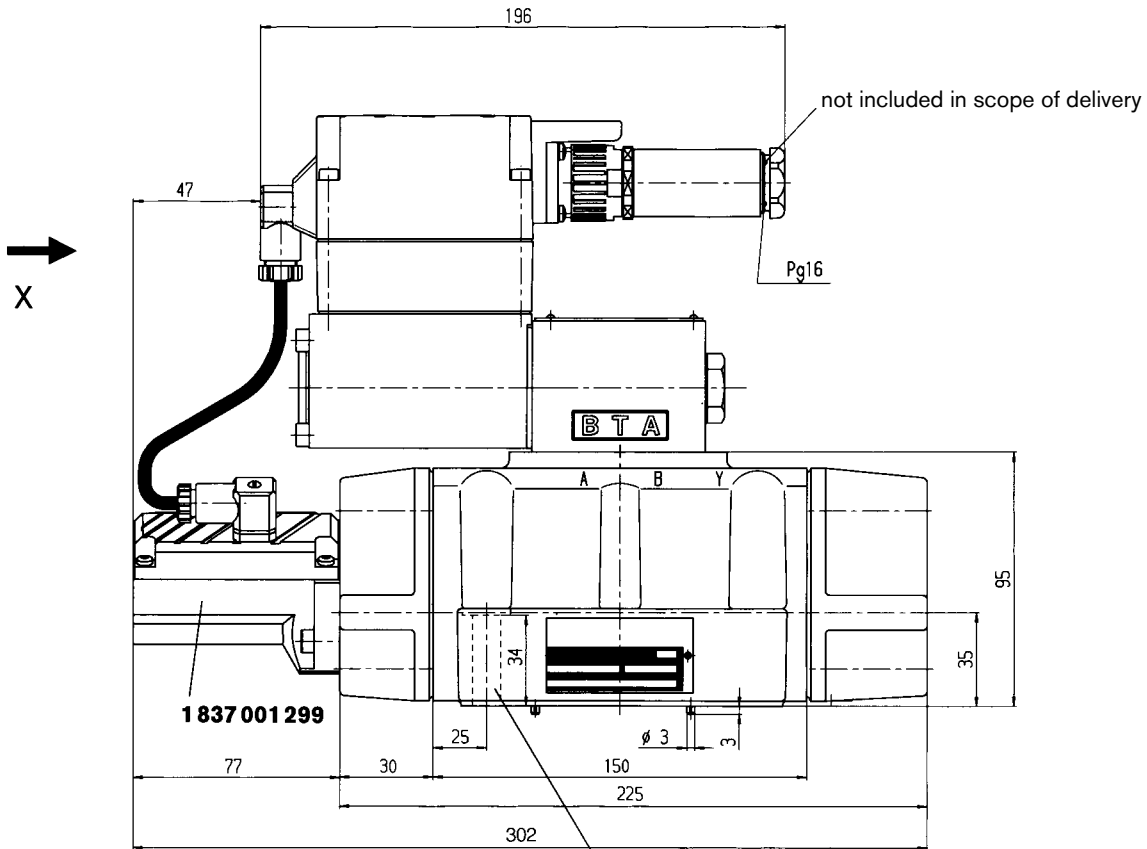




**Mounting hole configuration: NG10**  
 (ISO 4401-05-05-0-94), see page 14  
 For subplates, see catalogue section RE 45055




Required surface quality of mating component

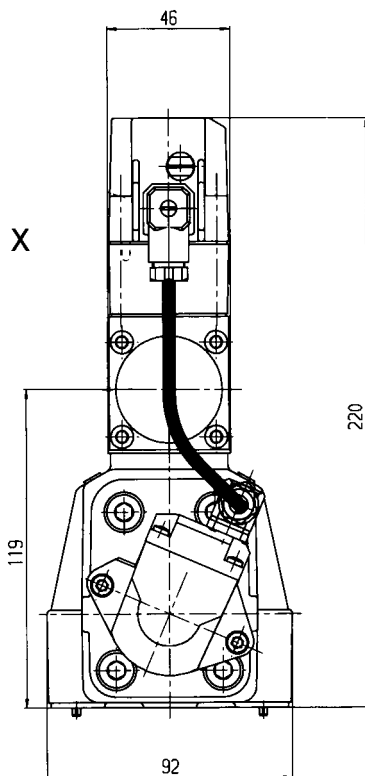


**Unit dimensions NG16** (nominal dimensions in mm)



-  2 x M6 x 45, DIN 912-10.9  $11^{+3}$  Nm
-  4 x M10 x 50, DIN 912-10.9  $50^{+10}$  Nm

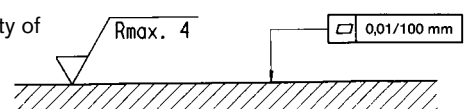
-  X, Y  $\varnothing 9 \times 2$
-  P, A, B, T  $\varnothing 23 \times 2,5$
-  Set **1817010275**



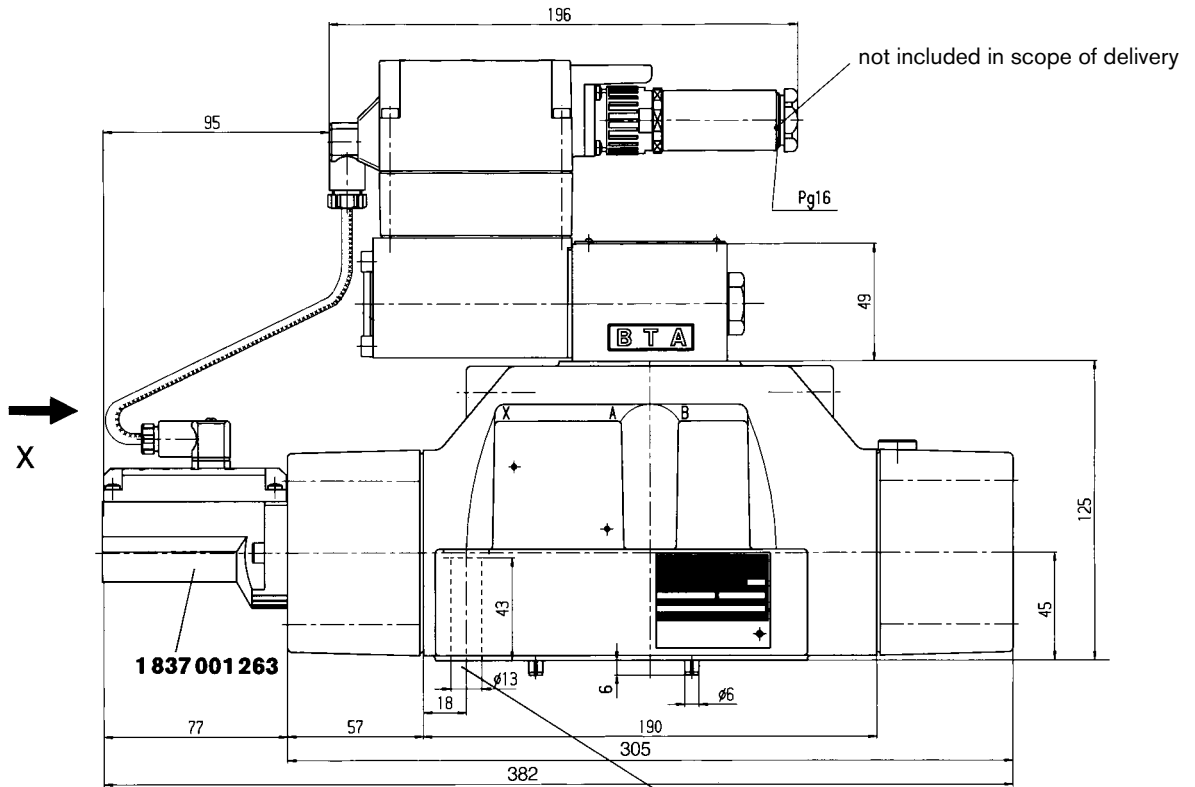
- M6 x 45 **2910151211**
- M10 x 50 **2910151301**


**Mounting hole configuration: NG16**  
 (ISO 4401-07-06-0-94), see page 14  
 For subplates, see catalogue section RE 45057




Required surface quality of mating component

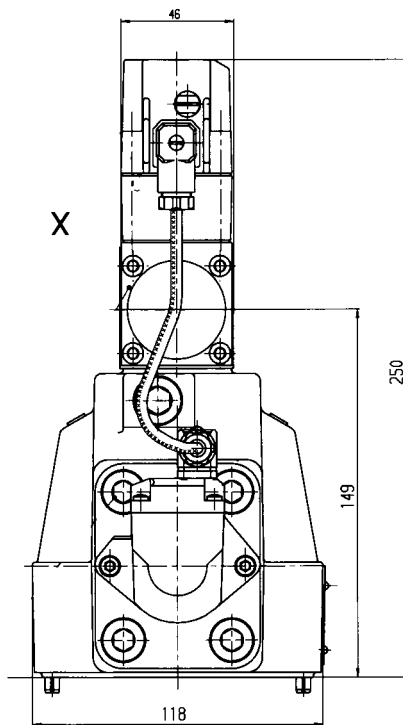


**Unit dimensions NG25** (nominal dimensions in mm)



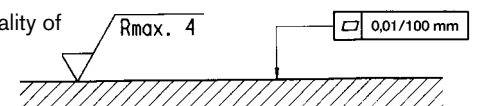
6 x  M12x60 DIN 912-10.9  
 = 90<sup>+30</sup> Nm  
**2910 151 354**

-  X, Y  $\varnothing 15 \times 2,5$
-  P, A, B, T  $\varnothing 28 \times 3$
-  Set **1817010273**



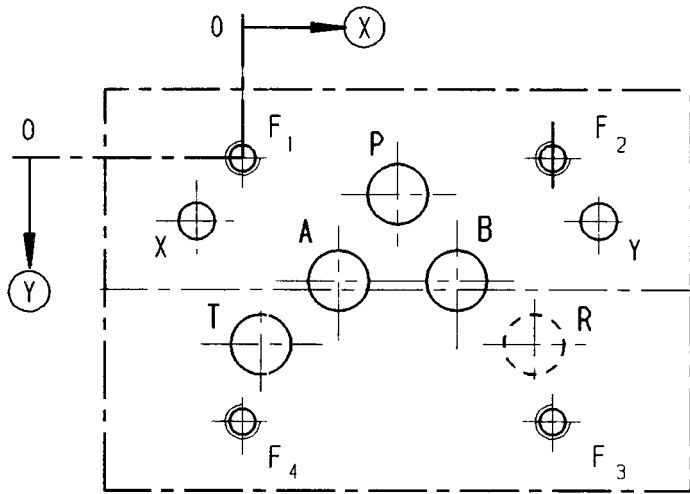
**Mounting hole configuration: NG25**  
 (ISO 4401-08-07-0-94), see page 15  
 For subplates, see catalogue section RE 45059

Required surface quality of mating component



**Mounting hole configurations** (nominal dimensions in mm)

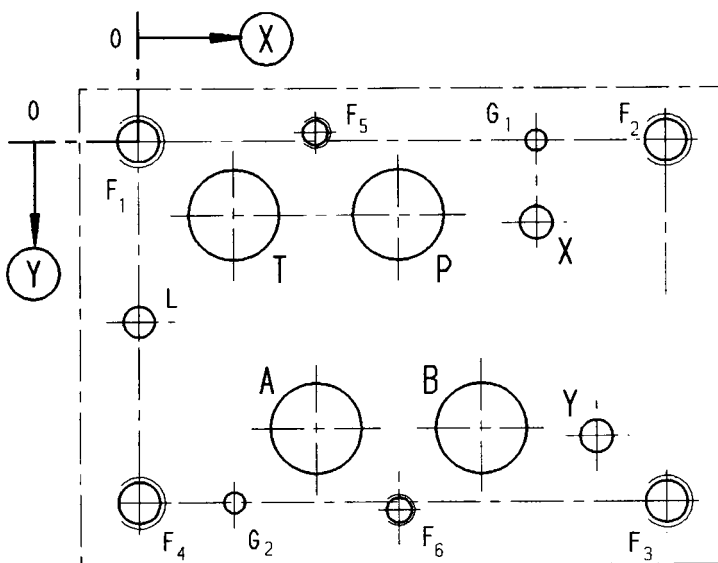
**NG10 – ISO 4401-05-05-0-94**



- <sup>1)</sup> Deviates from standard
- <sup>2)</sup> Thread depth:  
 Ferrous metal 1.5 x Ø\*  
 Non-ferrous 2 x Ø  
 \* (NG10 min. 10.5 mm)

	P	A	T	B	F <sub>1</sub>	F <sub>2</sub>	F <sub>3</sub>	F <sub>4</sub>	X	Y	R
⊗	27	16.7	3.2	37.3	0	54	54	0	-8	62	50.8
⊙	6.3	21.4	32.5	21.4	0	0	46	46	11	11	32.5
∅	10.5 <sup>1)</sup>	10.5 <sup>1)</sup>	10.5 <sup>1)</sup>	10.5 <sup>1)</sup>	M6 <sup>2)</sup>	M6 <sup>2)</sup>	M6 <sup>2)</sup>	M6 <sup>2)</sup>	6.3	6.3	10.5 <sup>1)</sup>

**NG16 – ISO 4401-07-06-0-94**



- <sup>1)</sup> Deviates from standard
- <sup>2)</sup> Thread depth:  
 Ferrous metal 1.5 x Ø  
 Non-ferrous 2 x Ø

	P	A	T	B	L	X	Y	G <sub>1</sub>	G <sub>2</sub>	F <sub>1</sub>	F <sub>2</sub>	F <sub>3</sub>	F <sub>4</sub>	F <sub>5</sub>	F <sub>6</sub>
⊗	50	34.1	18.3	65.9	0	76.6	88.1	76.6	18.3	0	101.6	101.6	0	34.1	50
⊙	14.3	55.6	14.3	55.6	34.9	15.9	57.2	0	69.9	0	0	69.9	69.9	-1.6	71.5
∅	20 <sup>1)</sup>	20 <sup>1)</sup>	20 <sup>1)</sup>	20 <sup>1)</sup>	6.3	6.3	6.3	4	4	M10 <sup>2)</sup>	M10 <sup>2)</sup>	M10 <sup>2)</sup>	M10 <sup>2)</sup>	M6 <sup>2)</sup>	M6 <sup>2)</sup>



## Notes

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