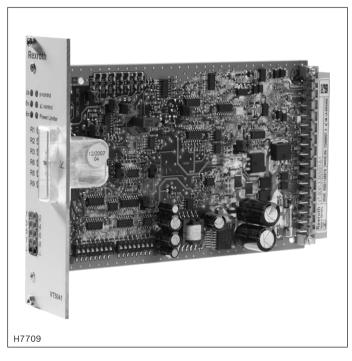
Edition: 2020-07 Replaces: 2013-06



# External control electronics for SYDFE1 control of the axial piston variable displacement pump A10VSO

# **Type VT 5041**



- ► Component series 3X
- ► Analog, euro-card format
- ▶ Part of the SYDFE1 pressure and flow control system (component series 1X, 2X and 3X) for the control of the axial piston variable displacement pump A10VSO ... with SYDFE1 control via valve type VT-DFP...2X

#### **Features**

- ► Implementation of the electronic functions of the SYDFE1 control; pressure and swivel angle control; optional power limitation
- ► Pressure controller circuitry can be adjusted and switched to two existing hydraulic fluid volumes (actuators plus lines)
- Minimum value generator for pressure and swivel angle controller
- ► Pressure-dependent leakage compensation (can be switched off)
- Switchable actual pressure value input (current, voltage, range)
- ▶ 6 LED displays on the front plate for the operating state
- ► Display instrument on the front plate for actual swivel angle value (optional)
- ► Power limitation with internal or external command value presetting (optional)

### **Contents**

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# **Ordering code**

VT 5041	_	ЗХ	1		_	0
01		02		03		04

01	External control electronics for SYDFE1 control of the axial piston variable displacement pump A10VSO	VT 5041
02	Component series 30 39 (30 39: unchanged technical data and pin assignment)	3X
Add	itional functions	
03	Without power limitation, without display instrument	1
	Without power limitation, with display instrument	2
	With power limitation, with display instrument	3
04	For swivel angle sensor IW9 (standard)	0

# **Available variants**

Туре	Material no.
VT 5041-3X/1-0	R901236404
VT 5041-3X/2-0	R901263598
VT 5041-3X/3-0	R901196678

#### **Functional description**

The analog control electronics VT5041-3X/... is designed as insertion card in euro format. It is provided with a command value input each for pressure and swivel angle (1) as a standard (optional power limitation). The actual pressure value is measured with a pressure transducer. The position transducer at the pump measures the actual swivel angle value. The measured actual values are processed in the amplifier (2) and (3) and compared with the provided command values. The minimum value generator (4) controls that only controller (6) or (10) which is allocated to the requested operating point is automatically activated. The output signal of the minimum value generator (4) becomes the command value for the valve control loop.

The optionally available power limitation is automatically activated by the provision of a suitable command value. The power command value can be provided internally or externally. If necessary, it limits the swivel angle command value by means of a minimum value generator (5). The resulting swivel angle command value can be measured at socket 7.

The actual valve value (position of the valve spool) is measured with an inductive position transducer. An oscillator/demodulator switch (7) enhances the signal. The control deviation is generated and processed in the controller for the valve spool position (8). The output signal of the valve controller (8) forms the command value for the self-timing power output stage (9) which controls the proportional solenoid of the valve.

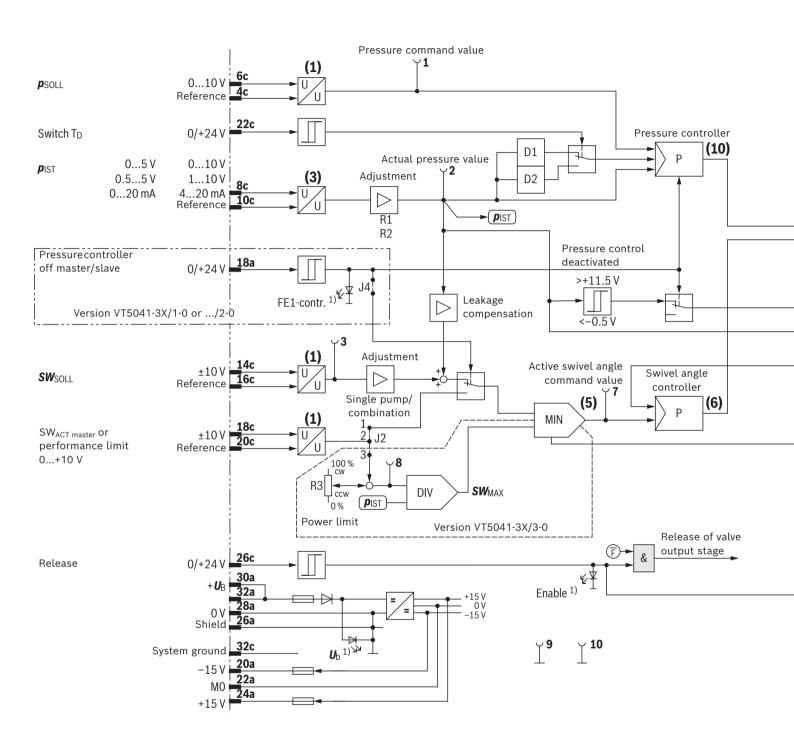
The control electronics is equipped with a fault message output where a voltage of 0 V is applied in case of error (= low-active). At the same time, the "Err." LED lights up. Depending on the jumper J1 configuration, the valve output stage can be de-energized in case of an error message. Causes for fault messages:

- ► Error in the internal voltage supply
- ► The actual pressure value is greater than the admissible system pressure (socket 2: **p**<sub>act</sub> > 11.5 V)
- ▶ No enable signal at port 26c
- ► Cable break or range of the swivel angle return exceeded
- ► Cable break or range of the valve spool return exceeded
- ► "Pressure transducer" cable break (with settings 4 ... 20 mA, 0.5 ... 5 V and 1 ... 10 V)
- ► Control error (control difference x controller amplification) is greater than 4 V (40%) for more than 1 second

In an error case, the electronics can be configured so that the output stage is de-energized and the valve spool is pressed to its mechanical end position. This causes the pump to swivel back. The error can only be acknowledged by resetting the enable signal.

See also "Block diagram" on page 4 and 5.

# Block diagram / pin assignment



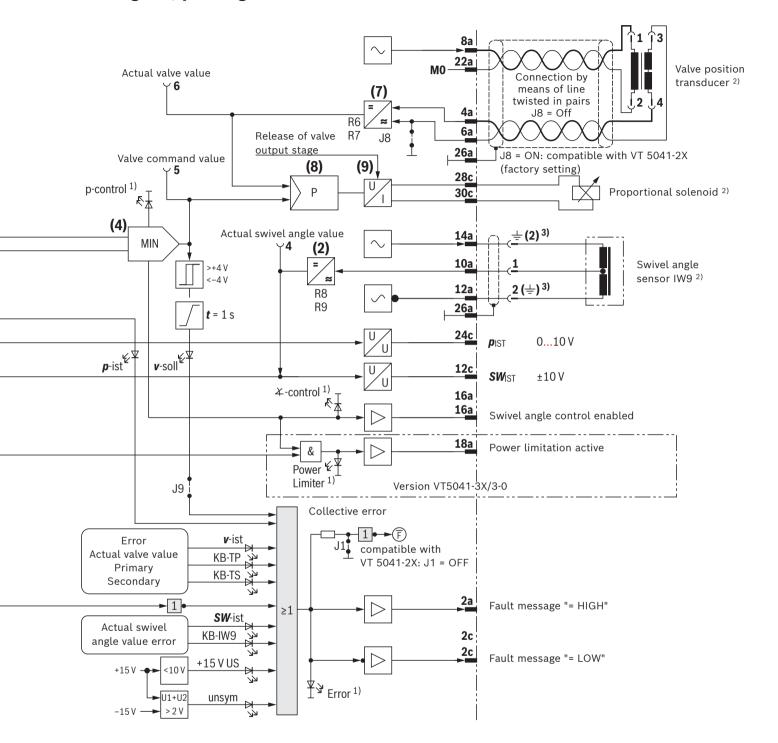
#### Abbreviations for signals

PCOMMANDPressure command valuePACTUALActual pressure valueSwitch TDOil volume switch-overSWCOMMANDSwivel angle command valueSWACTUALActual swivel angle valueSWACT masterActual master swivel angle valueFE1 contr.Pressure controller disabled

Function of the jumpers and switches on the electronic card see page 8.

For the meaning of the measuring sockets, display and adjustment elements (potentiometer) at the front plate, see page 9.

# Block diagram / pin assignment



#### Diagnostic LEDs on the printed circuit board

vcommandPersisting control deviation is too greatvactualActual valve value error - exceeding of rangepactualActual pressure value errorSWactualActual swivel angle value error - exceeding of rangeKB-TPValve position transducer cable break - primaryKB-TSValve position transducer cable break - secondary

KB-IW9 Swivel angle position sensor cable break
 +15 V US +15V undervoltage (internal power supply unit)
 asym Internal voltage supply

asymmetric

- $^{1)}$  LED display at the front plate (for meaning refer to page 9)
- 2) For further information with regard to the connection, see operating instructions 30011-B
- 3) Connection diagram for counterclockwise rotating systems in ()

# **Technical data**

(For applications outside these values, please consult us!)

Operating voltage	▶ Nominal	VDC	24; +40%10%
o p o . a	► Upper limit value	V	35
	► Lower limit value		21
Current	▶ Rated current	A	0.6
consumption	► Maximum	A	1.25
Analog input,	▶ Pressure <b>p</b> <sub>COMMAND</sub> 1)		0 10
command value	► Swivel angle <b>SW</b> <sub>COMMAND</sub> 1)	-	
	- Standard	V	±10
	- Regenerative	V	0 10
	▶ Power 1)		
	$- (\boldsymbol{p} \times \mathbf{S} \boldsymbol{W})_{\text{max}}$	V	0 10
	- SW <sub>ACT master</sub>	V	±10
Analog input,	▶ Pressure <b>p</b> <sub>ACT</sub>		
actual value	- Voltage 1)	V	0 5, 0 10
			0.5 5, 1 10
	- Current	mΑ	$0 \dots 20, 4 \dots 20; \mathbf{R}_{B} = 100 \Omega$
Enable input (PLC)		V	>12
Analog output	► Output stage		
	- Solenoid current	Α	$2.5; \mathbf{R}_{20} = 2 \Omega$
	► Oscillator		
	- Frequency	kHz	5.4
	<ul> <li>Amplitude for IW9 (actual swivel angle value)</li> </ul>	V	1 (port 12a /14a)
	- Amplitude for DM2 (actual valve value)	V	3.6 (port 8a)
	► Signal voltage outputs		
	- Actual pressure value	V	0 10
	– Actual swivel angle value	V	-10 +10 (-100% +100%)
Auxiliary voltages fo	r external use (I <sub>max</sub> = 10 mA)	V	±15; +2%6%
Measuring sockets,	► Pressure command value (p <sub>COMMAND</sub> ) 1	V	0 10 (0 +100%; $\mathbf{R}_i$ = 2 kΩ)
function and	► Actual pressure value ( <b>p</b> <sub>ACT</sub> ) 2	V	0 10 (0 +100%; $\mathbf{R}_i$ = 2 kΩ)
number	► Swivel angle command value ( <b>sW</b> <sub>COMMAND)</sub> 3	V	$\pm 10 \ (\pm 100\%; \mathbf{R}_i = 2 \ k\Omega)$
	► Actual swivel angle value (SW <sub>ACT</sub> ) 4	V	$\pm 10 \ (\pm 100\%; \mathbf{R}_i = 2 \ k\Omega)$
	► Valve command value (x_ <b>v</b> <sub>command</sub> ) 5	V	$\pm 10 \ (\pm 100\%; \mathbf{R}_i = 2 \ k\Omega)$
	► Actual valve value (x_ <b>v</b> <sub>act</sub> ) 6	V	$\pm 10 \ (\pm 100\%; \mathbf{R}_i = 2 \ k\Omega)$
	► Active swivel angle command value 7	V	$\pm 10 \ (\pm 100\%; \mathbf{R}_i = 2 \ k\Omega)$
	► Power limit ( <b>P</b> <sub>max</sub> ) 8	V	0 10 (0 +100%; $\mathbf{R}_i$ = 2 kΩ)
	► Reference 9, 10		
Message outputs	► Swivel angle control enabled	V	<b>U</b> <sub>B</sub> 3 ( <b>I</b> <sub>max</sub> = 20 mA)
	► Power limitation active	V	<b>U</b> <sub>B</sub> 3 ( <b>I</b> <sub>max</sub> = 20 mA)
Fault messages	► Low-active	V	$U_{\rm B} \dots 3 \ (I_{\rm max} = 20 \ {\rm mA}); \ {\rm error \ at} \ U < 1$
	► High-active	V	<b>U</b> <sub>B</sub> 3 ( <b>I</b> <sub>max</sub> = 20 mA)
Transducer type	► Swivel angle		
	- IW9 (inductive position transducer)		Throttle circuit; ±4 mm; 3-conductor connection
	► Valve		
	- DM2 (inductive position transducer)		Trafo circuit; ±0.6 mm; 4-conductor connection
Type of connection	► Compatibility		32-pole male multipoint connector, DIN 41612, design D
Type of confidential	- Companionity		

<sup>1)</sup>  $R_e > 50 \text{ k}\Omega$ 

# **Technical data**

(For applications outside these values, please consult us!)

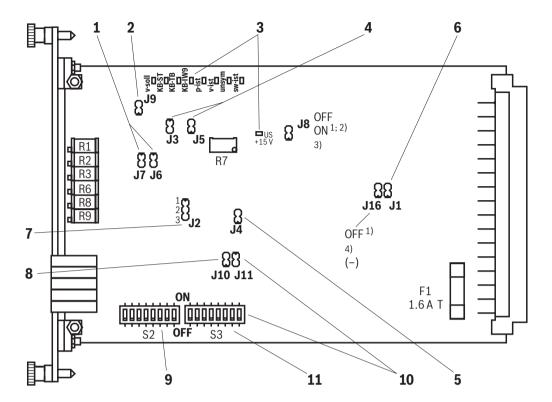
Front plate	▶ Height		3 HE (128.4 mm)
dimensions	► Conductor path side width		1 TE
	► Component side width		
	- Version "1"		5 TE
	- Version "2" and "3"		7 TE
Operating tempor	erature range	°C	0 +50
Storage tempera	ature range	°C	-20 +70
Weight	► Without display	kg	0.19
	► With display	kg	0.21

# Environmental compatibility for the areas EMC, climate and mechanical load

Mechanical load	Test according to EN 60068-2 / IEC 68-2 / DIN 40046
EN 60068-2-6:1995, vibrations, sine-shaped	10 cycles / 10 500 10 Hz / Δf = 1 oct./min. / max. 2 g
IEC 68-2-36: 1973 / DIN 40046-24: 1977, vibrations, random (broadband noise)	20 500 Hz / 2.2 g <sub>RMS</sub> / 0.01 g <sup>2</sup> /Hz / 30 min per axis
EN 60068-2-27:1993, shocking	Half-sine 15 g / 11 ms, 3 x each in positive and in negative direction per axis
Electro-magnetic compatibility (EMC)	
Interference resistance	Testing according to EN 61000-6-2:2005, VDE 0839 Part 6-2
ESD - EN 61000-4-2:1995, +A1:1998 +A2:2000, IEC 1000-4-2	Air discharge SG 3 / BWK A Contact discharge SG 4 / BWK A
Burst - EN 61000-4-4:2004, IEC 1000-4-4	Repetition rate 5KHz / 100KHz Ub: SG 3 / BWK A Data line: SG 4 / BWK A
Surge – EN 61000-4-5:2006, IEC 1000-4-5	Ub: SG 1 / BWK B
HF fields - EN 61000-4-6:2007, + corrigendum 08/2007, IEC 1000-4-6 (conducted)	Ub: SG 3 / BWK A
Interference emission	Testing according to EN 61000-6-3:2007, VDE 0839 Part 6-3
IEC/CISPR16-2-1:2005-09, point 7.4.1 Limit values according to EN 61000-6-3:2007 IEC/CISPR16-1-2:2006-08, point 4.3 0.15 30 MHz; table 1, line 3	

SG = severity level BWK = evaluation criterion

# **Electronic card:** Display and adjustment elements



1	Leakage	Jumper	
	compensation	J6	J7
	Off	OFF	OFF
	4%	OFF	ON
	6%	ON	OFF
	10%	ON	ON

2	Valve command value monitoring	Jumper J9	
	On	ON	
	Off <sup>2)</sup>	OFF	

3	Diagnostic LEDs		
	For a description,		
	see page 5 and the		
	operating instructions		
	30011-B		

4	Regenerative	Jun	per
	operation	J3	J5
	On	ON	OFF
	Off	OFF	ON

5	Function pin 18a <sup>5)</sup>	Jumper J4
	Pressure control on/off	OFF
	Master/slave on/off	ON

6	Valve switch-off in case of error	Jumper J1				
	Active	OFF 2)				
	Inactive	ON				

7	Selection for	Jumper			
	analog input at pin 18c	J2 Bridge			
	Actual master swivel angle value	1-2			
	External power limitation	2-3			

p gain pressure

controller

8.0

4.8

4.0

3.0

2.4

2.0

8	Actual pressure value gain	Jumper J10					
	1-fold	OFF					
	2-fold	ON					

**Jumper** 

J11

OFF

OFF

ON

ON

ON

ON

Switch S3

.8

OFF

ON

OFF

ON

OFF

ON

.7

OFF

OFF

OFF

OFF

ON

ON

9	_	nal adjustment	Switch S2									
	ac	tual pressure value	.1	.2	.3	.4	.5	.6	.7	.8		
	٧	0 10 V	OFF	OFF	OFF	OFF	OFF	OFF	ON	ON		
	E 1 10 V		OFF	OFF	OFF	OFF	ON	OFF	OFF	ON		
	D 0 5 V		OFF	OFF	ON	ON	OFF	OFF	ON	ON		
	F 0.5 5 V B 0 20 mA C 420 mA		OFF	OFF	ON	ON	ON	OFF	OFF	ON		
			ON	ON	OFF	OFF	OFF	OFF	ON	ON		
			ON	ON	OFF	OFF	ON	ON	OFF	OFF		

L		420	mA	ON	ON	OFF	OFF	ON	ON	OFF	OFF			
ı		Vo	lume	adjus	tment	of p	essur	e cor	ntroll	er			ON	Bridge closed
		Input Switch S3		53		Input Switch S3				53	(	OFF	Bridge open	
	s	witch					switc	h						Factory setting
	T	o = OFF	.1	.2	.3		$T_D = 0$	N	.4	.5	.6			
		-5 O I	OEE	OEE	OEE		12.5	1	OEE	OEE	OEE	4)		

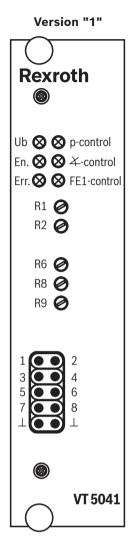
- 11 OFF 7.5 l OFF ON OFF 30.0 L OFF ON OFF 10.0 l ON OFF 45 l OFF ON ON ON 15.0 l ON OFF  $\mathsf{ON}$ 60 l ON OFF ON 20.0 l OFF ON ON 75 l OFF ON ON 25.0 l ON ON ON 90 l ON ON ON
- 1) Factory setting

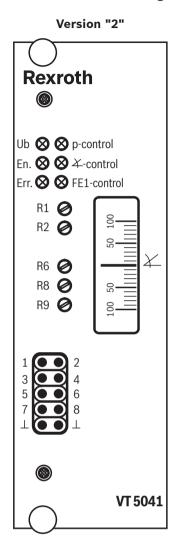
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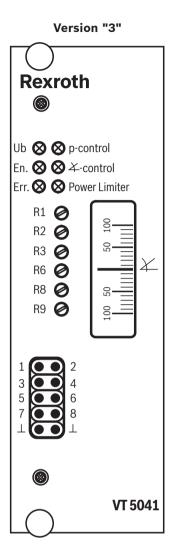
- 2) Compatible with VT 5041-2X
- 3) Reference for position transducer
- Reference for actual pressure value
- 5) Only version "1" and "2" (without power limitation)

Measuring sockets, display and adjustment elements (potentiometer) at the front plate see page 9.

# Front plate: Display and adjustment elements, measuring sockets







#### **LED displays**

Ub (green)

En. (green)

Enable available

Err. (red)

p-control (yellow)

Fault/collective error

Pressure control enabled

Fullow

F

# Adjustment elements (potentiometer)

R1 Zero point of actual pressure value
 R2 Actual pressure value gain
 R3 Setting of the power limit
 R6 Zero point of actual valve value
 R8 Zero point of actual swivel angle value
 R9 Gain of actual swivel angle value

#### Measuring sockets ( $R_i = 2 k\Omega$ )

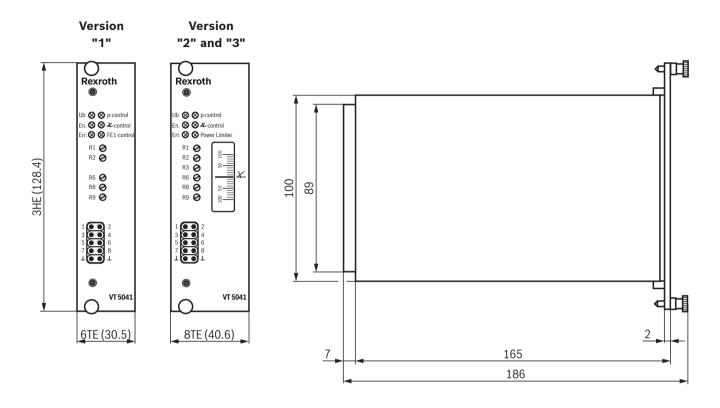
- 1 Pressure command value 0...+10 V
- 2 Actual pressure value 0...+10 V
- 3 Swivel angle command value ±10 V
- 4 Actual swivel angle value ±10 V
- 5 Valve command value ±10 V
- 6 Actual valve value ±10 V
- 7 Active swivel angle command value ±10 V
- 8 Power limit 0...+10 V
- ⊥ Reference for measured values

#### Display (measuring instrument)

🔀 Actual swivel angle value display in %

# **Dimensions**

(dimensions in mm)



# Accessories (separate order)

Card holder	Material number	Data sheet	
Open card holder VT 3002-1-2X/32D	_	29928	
Power supply unit	Material number	Data sheet	
Type VT-NE32-1X, compact power supply unit 115/230 VAC → 24 VDC	_	29929	
► Output 1 (60 W) to supply VT-5041	-	-	
► Output 2 (24 W) to supply pressure transducers; e.g. type HM20	-	30272	

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It must be remembered that our products are subject to a natural process of wear and aging.

# **Notes**

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